Servo amplifier

mcDSA-S45-HC

Article number: 1511178

Picture similar

Technical data

Supply voltages	
Electronic supply voltage Ue*1	9..30 V
Electronic current consumption@ Ue=24V*2	typ. 60 mA
Power supply voltage Up*3	9..60 V
Output current	
Max. output current	20 A
Continuous output current @ Up=24V*4	10 A
Continuous output current @ Up=48V*4	9 A
PWM	
Output voltage	85% Up
PWM frequency	32 kHz
Mechanical	
Size LxWxH (HC Version)	110 x 39 x 77 mm
Weight (HC Version)	295 g
Environment	
Protection class	IP20
Ambient temperature (operation)*5	-40..70 °C
Ambient temperature (storage)	-40..85 °C
Rel. humidity (non-condensing)	5..90 %
CAN bus	
Protocol	DS301
Device profile	DS402
Max. baudrate	1 Mbit/s
CAN specification	2.0B
Galvanically isolated	no

Sensor supply (Encoder)	
Output voltage	5 V
Max. output current	0.2 A
Incremental encoder	
Type	incremental
Signals	A,/A,B,/B,Inx,/Inx
Max. freqency (per channel)	500 kHz
Input voltage (24V tolerant)	0..5 V
Signal type	differential, open collector, single ended
Digital inputs	
Number - digital inputs	8 (Din0..7)
Low voltage	0..5 V
High voltage	8..30 V
Digital outputs	
Number	2 (Dout0..1)
Continuous output current	1.5 A
Load	resistive, inductive
Output voltage	Electronic supply voltage Ue
Signal type	positive switching
Analog inputs	
Number	2 (Ain0..1)
Signal type - Ain0	+/- 10 V, 12 Bit, differential
Signal type - Ain1	+/- 10 V, 12 Bit, single ended

*1 No reverse polarity protection, the destruction limit is at overvoltage of >= 33V or short-term peak voltage of 37V < 1s
*2 power amplifier switched off, 5V output (sensor supply) is free
*3 No reverse polarity protection, the destruction limit is at overvoltage of >= 80V
*4 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C (t >40 °C derating), RMS current: 10 A → 8.1 Aeff, 9 A → 7.3 Aeff
no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current
*5 Hex-Switches should be not used at T < -25°C (setting of node ID only possible by firmware parameters)

Additional technical data are available in mcManual.

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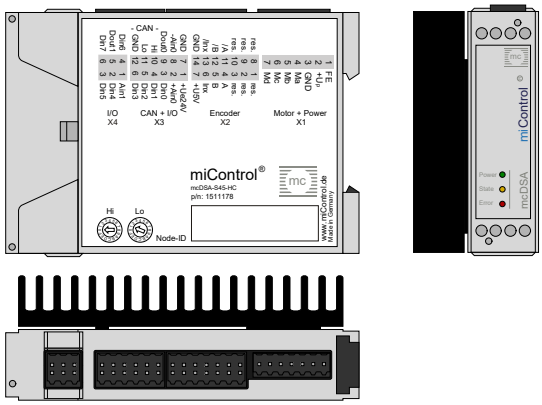
Scheme



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Terminal assignment

X1	Motor	
1	FE	Functional earth
2	+Up	Power supply voltage
3	GND	Ground for power supply voltage
4	Ma	Motor phase A
5	Mb	Motor phase B
6	Mc	Motor phase C
7	Md	Motor phase D
X2	Inc. encoder	
1	res.	Reserved
2	res.	Reserved
3	res.	Reserved
4	A	Inc. encoder, A channel
5	B	Inc. encoder, B channel
6	Inx	Inc. encoder, index channel
7	+U5V	5V output voltage for sensor supply Sensors: encoder
8	res.	Reserved
9	res.	Reserved
10	res.	Reserved
11	/A	Inc. encoder, A channel inverted
12	/B	Inc. encoder, B channel inverted
13	/Inx	Inc. encoder, index channel inverted
14	GND	Ground for sensor supply Notice: don't connect with system GND
X3	I/O's and CAN	
1	+Ue24V	Electronic supply voltage
2	+Ain0	Analog input 0, plus
3	Din0	Digital input 0
4	Din1	Digital input 1
5	Din2	Digital input 2
6	Din3	Digital input 3
7	GND	Ground for electronic supply voltage
8	-Ain0	Analog input 0, minus
9	Dout0	Digital output 0
10	CAN Hi	CAN High
11	CAN Lo	CAN Low
12	CAN GND	CAN Ground

X4	I/O's	
1	Ain1	Analog input 1
2	Din4	Digital input 4
3	Din5	Digital input 5
4	Din6	Digital input 6
5	Dout1	Digital output 1
6	Din7	Digital input 7

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