# iContro

#### SINGLE AXIS BLDC SERVO AMPLIFIER mcDSA-E56-LP



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## Instruction notes for electrical personnel

### UL-Recognition (UL 61800-5-1 and CSA C22.2 No 274-13)

While operating the mcDSA-E56-LP in USA or Canada it is essential to observe the following information.

Input / Output Ratings						
	Input ratings: DC Voltage Isolated Power Source					
Circuit	Input Voltage (V DC)	Input Current (ADC)	Frequency (Hz)	Base Frequency PWM (kHz) / Duty Cycle	Phases	
Control	24	1.6	DC	-	1	
Power	24	9.5	DC	-	1	
Power	60	9	DC	-	1	
	Output ratings:					
Circuit	Output Voltage (V DC)	Output Current (A)	Frequency (Hz)	Base Frequency PWM (kHz) / Duty Cycle	Phases	
Power Continuous	24	9.5	0 5k	25, 32, 50	3	
Ratings	60	9	0 5k	25, 32, 50	3	
Power	Max 60	50	0 5k	Ton = x s Toff = 120 s	3	
Duty Cycle Rating		Current and Ton values can be chosen freely if the I <sup>2</sup> t is under 1500 A <sup>2</sup> s with following formula:				



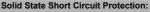
## **General Requirements:**

· Open type brushless DC (BLDC) servo motor controller

- Maximum Surrounding Air Temperature 40°C
- . Installation on a secondary side of an PELV isolated power supply (DVC A circuit)
- For use in pollution Degree 2 and overvoltage Category II environments only
- · Motor overtemperature sensing is not provided by the drive. Where required, integral thermal protection shall be provided on or in the motor(s).

I<sup>2</sup> x Ton <= 1500 A<sup>2</sup>s = (I<sup>2</sup>t)max

Multiple rated equipment (See Input / Output Ratings)



USA: Integral solid state short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the National Electrical Code and any additional local codes.

Important

Canada: Integral solid state short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the Canadian Electrical Code, Part I.



Motor Overload Protection: provided by IxT current limit at 115% rated motor load

The motor is protected by a dynamic current limitation (IxT) which must be adjusted for each used type of motor. Information on peak current, continuous current and permissible overload time have to be gathered from the motor manufacturer.

The following parameters have to be set:

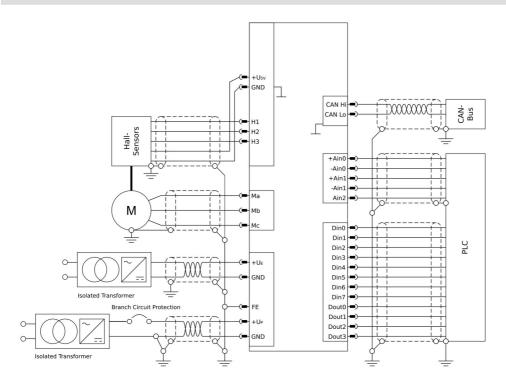
- 3224.00h Mode (CURR\_DynLimitMode)
- 3224.01h Peak Current (CURR\_DynLimitPeak)
- 3224.02h Continuous Current (CURR DynLimitCont)
- 3224.03h Time (CURR DynLimitTime)

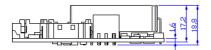
The dynamic current limitation is set back to default with power loss. Therefore the motor has to cool down to ambient temperature before restart. Cooling down times are provided by the motor manufacturer. A restart without enough cooling down time can damage the motor and drive controller even if the dynamic current limiting is set properly. To set the parameters please read the manual.

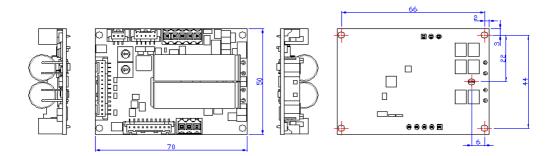


Branch Circuit Protection:	Field wiring terminals:		
UL 489 circuit breaker 20A, 60VDC, 1 pole, C standard, 10kA SCCR	<ul> <li>Use 60°C/75°C copper conductors only</li> <li>X2 – X5 AWG 24, X1/X6 - AWG 16</li> </ul>		

### Wiring Diagram (Principle Circuit Diagram) and Dimension







Modul mass: 50 g