

## Instruction notes for electrical personnel



### UL-Recognition (UL 61800-5-1 and CSA C22.2 No 274-13)

While operating the mcDSA-E32-M in USA or Canada it is essential to observe the following information.

Input / Output Ratings					
Input ratings: DC Voltage Isolated Power Source					
Circuit	Input Voltage (V DC)	Input Current (A DC)	Frequency (Hz)	Base Frequency PWM (kHz) / Duty Cycle	Phases
Control	24	3.2	DC	-	1
Power	24	12	DC	-	1
	60	10	DC	-	1
Output ratings:					
Circuit	Output Voltage (V DC)	Output Current (A DC)	Frequency (Hz)	Base Frequency PWM (kHz) / Duty Cycle	Phases
Power Continuous Ratings	24	12	0 .. 50k	25, 32, 50	3
	60	10	0 .. 50k	25, 32, 50	3
Power Duty Cycle Rating	60	40	0 .. 50k	Ton = x s Toff = 60 s	3

Current and Ton values can be chosen freely if the I<sup>2</sup>t is under 6240 A<sup>2</sup>s with following formula:  
I<sup>2</sup> x Ton <= 6240 A<sup>2</sup>s = (I<sup>2</sup>)max



Important

### General Requirements:

- Open type brushless DC (BLDC) servo motor controller
- Maximum Surrounding Air Temperature 40°C
- Installation on a secondary side of an PELV isolated power supply (DVC A circuit)
- For use in pollution Degree 2 and overvoltage Category II environments only
- Motor overtemperature sensing is not provided by the drive. Where required, integral thermal protection shall be provided on or in the motor(s).
- Multiple rated equipment (See **Input / Output Ratings**)



Important

### Solid State Short Circuit Protection:

**USA:** Integral solid state short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the National Electrical Code and any additional local codes.

**Canada (EN):** Integral solid state short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the Canadian Electrical Code, Part I.

**Canada (FR):** La protection intégrale contre les courts-circuits à semi-conducteurs ne fournit pas de protection des circuits de dérivation. La protection du circuit de dérivation doit être fournie conformément au Code canadien de l'électricité, partie I.



Important

**Motor Overload Protection:** provided by IxT current limit at 115% rated motor load

The motor is protected by a dynamic current limitation (IxT) which must be adjusted for each used type of motor. Information on peak current, continuous current and permissible overload time have to be gathered from the motor manufacturer.

The following parameters have to be set:

- 3224.00h - Mode (CURR\_DynLimitMode)
- 3224.01h - Peak Current (CURR\_DynLimitPeak)
- 3224.02h - Continuous Current (CURR\_DynLimitCont)
- 3224.03h - Time (CURR\_DynLimitTime)

The dynamic current limitation is set back to default with power loss. Therefore the motor has to cool down to ambient temperature before restart. Cooling down times are provided by the motor manufacturer. A restart without enough cooling down time can damage the motor and drive controller even if the dynamic current limiting is set properly. To set the parameters please read the manual.

### SCCR:

Suitable For Use on A Circuit Capable of Delivering Not More Than 280 rms Symmetrical Amperes, 60 Volts Maximum.



Important

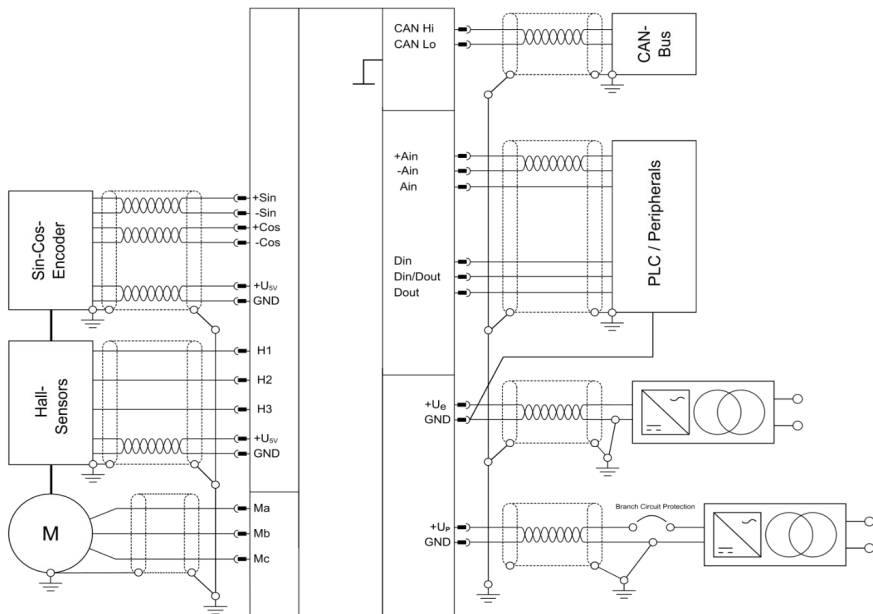
### Branch Circuit Protection:

UL 489 circuit breaker  
30A, 60VDC, 1 pole, C standard, 14kA SCCR

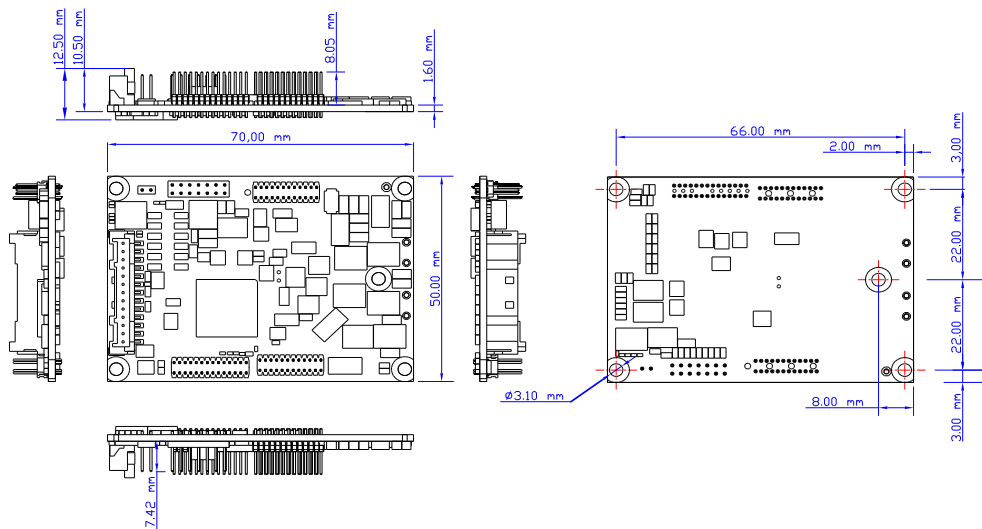
### Factory wiring terminals:

- Use 60°C/75°C copper conductors only

# Wiring Diagram (Principle Circuit Diagram) and Dimension



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**Modul mass:**

50 g