

# Servo amplifier

## mcDSA-E22XC

Article number: 1514089

 Certification: 


Picture similar

### Technical data

Supply voltages	
Electronic supply voltage $U_e^{*2}$	9..30 V
Electronic current consumption @ $U_e=24V^{*3}$	typ. 70 mA
Power supply voltage $U_p^{*4}$	9..60 V
Output current	
Max. output current	160 A
Continuous output current (certified UL) <sup>*5</sup>	
@ $U_p \leq 24V$	44 A
@ $U_p \leq 60V$	40 A
Continuous output current (not certified) <sup>*6</sup>	
@ $U_p \leq 24V$	70 A
@ $U_p \leq 48V$	63 A
PWM	
Output voltage	90% $U_p$
PWM frequency	25, 32 <sup>*7</sup> , 50 kHz
Mechanical	
Size LxWxH	111 x 100 x 39 mm
Weight	400 g
Environment	
Protection class	IP20
Ambient temperature (operation) <sup>*8</sup> (certified UL)	-40..40 °C
Ambient temperature (operation) <sup>*8</sup> (not certified)	-40..70 °C
Ambient temperature (storage)	-40..85 °C
Rel. humidity (non-condensing)	5..90 %
CAN bus	
Protocol	DS301
Device profile	DS402
Max. baudrate	1 Mbit/s
CAN specification	2.0B
Galvanically isolated	no

Sensor supply (Encoder/Hall)	
Output voltage	5 V
Max. output current	0.2 A
Encoder	
Type	sin / cos
Signals	+Sin,-Sin,+Cos,-Cos
Resolution	13 bit per sine period
Input voltage	1 V peak-peak, differential
Signal type	sine/cosine, analog, differential
Digital inputs	
Number - digital inputs	4 (Din0..3)
Low voltage	0..5 V
High voltage	8..30 V
Digital outputs	
Number	1 (Dout0)
Continuous output current (certified UL)	1.5 A
Load	resistive, inductive
Output voltage	Electronic supply voltage $U_e$
Signal type	positive switching
Analog inputs	
Number	1 (Ain0)
Signal type - Ain	+/- 10 V, 12 Bit, differential

\*1 The certified performance data must be observed (see UL Instruction Note)

\*2 No reverse polarity protection, the destruction limit is at overvoltage of  $\geq 33V$  or short-term peak voltage of  $37V < 1s$

\*3 power amplifier switched off, 5V output (sensor supply) is free

\*4 No reverse polarity protection, the destruction limit is at overvoltage of  $\geq 80V$

\*5 connector cable with max. possible cable cross-section, PWM frequency 32 kHz (asymmetrical), ambient temperature 40 °C, I/O's and 5V output active, RMS current: 44 A  $\rightarrow$  36 Aeff, 40 A  $\rightarrow$  33 Aeff

\*6 connector cable with max. possible cable cross-section, PWM frequency 32 kHz (asymmetrical), ambient temperature 40 °C, I/O's and 5V output free, RMS current: 70 A  $\rightarrow$  57 Aeff, 63 A  $\rightarrow$  51 Aeff

no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

\*7 default value

\*8 Hex-Switches should be not used at  $T < -25^\circ C$  (setting of node ID only possible by firmware parameters)

Additional technical data are available in mcManual.



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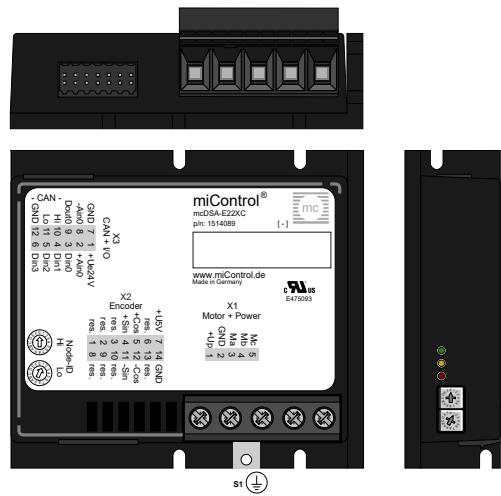
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## Scheme



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## Terminal assignment

X1 Motor		
1	+Up	Power supply voltage
2	GND	Ground for power supply voltage
3	Ma	Motor phase A
4	Mb	Motor phase B
5	Mc	Motor phase C
X2 Encoder		
1	res.	Reserved
2	res.	Reserved
3	res.	Reserved
4	+Sin	Encoder, plus sine signal
5	+Cos	Encoder, plus cosine signal
6	res.	Reserved
7	+U5V	5V output voltage for sensor supply Sensors: encoder
8	res.	Reserved
9	res.	Reserved
10	res.	Reserved
11	-Sin	Encoder, minus sine signal
12	-Cos	Encoder, minus cosine signal
13	res.	Reserved
14	GND	Ground for sensor supply Notice: don't connect with system GND
X3 I/O's and CAN		
1	+Ue24V	Electronic supply voltage
2	+Ain0	Analog input 0, plus
3	Din0	Digital input 0
4	Din1	Digital input 1
5	Din2	Digital input 2
6	Din3	Digital input 3
7	GND	Ground for electronic supply voltage
8	-Ain0	Analog input 0, minus
9	Dout0	Digital output 0
10	CAN Hi	CAN High
11	CAN Lo	CAN Low
12	CAN GND	CAN Ground
S1 Screw (M4)		
-	FE	Functional earth