

# Servo amplifier

## mcDSA-E27

Article number: 1511113



Picture similar

**Technical data**

<b>Absolute maximum rating (destruction limits)</b>		<b>Sensor supply (Encoder)</b>
Power supply voltage Up no polarity reversal protection	80 V	Output voltage 5 V
Continuous Electronic supply voltage Ue no polarity reversal protection	33 V	Max. output current 0.2 A
Short term peak voltage < 1s Ue no polarity reversal protection	37 V	<b>Encoder</b>
<b>Power</b>		Type $\sin / \cos$
Electronic supply voltage Ue	9..30 V	Signals $+Sin, -Sin, +Cos, -Cos$
Electronic current consumption @ Ue=24V*1	typ. 70 mA	Resolution 13 bit per sine period
Power supply voltage Up	9..60 V	Input voltage 1 V peak-peak, differential
Max. output current	100 A	Signal type sine/cosine, analog, differential
Continuous output current @ Up=24V*2	35 A	<b>Digital inputs</b>
Continuous output current @ Up=48V*2	26 A	Number - digital inputs 7 (Din0..6)
<b>PWM</b>		Low voltage 0.5 V
Output voltage	100% Up	High voltage 8..30 V
PWM frequency	25, 32*3, 50 kHz	<b>Digital outputs</b>
<b>Mechanical</b>		Number 2 (Dout0..1)
Size LxWxH	111 x 100 x 31 mm	Continuous output current 1.5 A
Weight	380 g	Load resistive, inductive
<b>Environment</b>		Output voltage Electronic supply voltage Ue
Protection class	IP20	Signal type positive switching
Ambient temperature (operation)*4	-40..70 °C	<b>Analog inputs</b>
Ambient temperature (storage)	-40..85 °C	Number 2 (Ain0..1)
Rel. humidity (non-condensing)	5..90 %	Signal type - Ain0 +/- 10 V, 12 Bit, differential
<b>CAN bus</b>		Signal type - Ain1 +/- 10 V, 12 Bit, single ended
Protocol	DS301	
Device profile	DS402	
Max. baudrate	1 Mbit/s	
CAN specification	2.0B	
Galvanically isolated	yes	

\*1 power amplifier switched off, 5V output (sensor supply) is free

\*2 connector cable with max. possible cable cross-section, PWM frequency 25 kHz, ambient temperature 40 °C (t &gt; 40 °C derating), RMS current: 35 A → 28.5 Aeff, 26 A → 21.2 Aeff

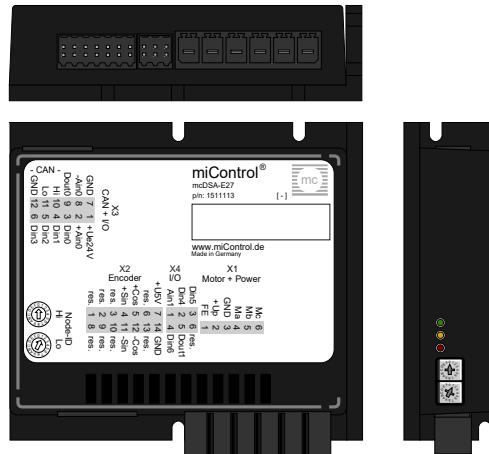
\*3 no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

\*4 default value

\*4 Hex-Switches should be not used at T &lt; -25°C (setting of node ID only possible by firmware parameters)

Additional technical data are available in mcManual.

## Scheme



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## Terminal assignment

X1	Motor	
1	FE	Functional earth
2	+Up	Power supply voltage
3	GND	Ground for power supply voltage
4	Ma	Motor phase A
5	Mb	Motor phase B
6	Mc	Motor phase C
X2	Encoder	
1	res.	Reserved
2	res.	Reserved
3	res.	Reserved
4	+Sin	Encoder, plus sine signal
5	+Cos	Encoder, plus cosine signal
6	res.	Reserved
7	+U5V	5V output voltage for sensor supply Sensors: encoder
8	res.	Reserved
9	res.	Reserved
10	res.	Reserved
11	-Sin	Encoder, minus sine signal
12	-Cos	Encoder, minus cosine signal
13	res.	Reserved
14	GND	Ground for sensor supply Notice: don't connect with system GND
X3	I/O's and CAN	
1	+Ue24V	Electronic supply voltage
2	+Ain0	Analog input 0, plus
3	Din0	Digital input 0
4	Din1	Digital input 1
5	Din2	Digital input 2
6	Din3	Digital input 3
7	GND	Ground for electronic supply voltage
8	-Ain0	Analog input 0, minus
9	Dout0	Digital output 0
10	CAN Hi	CAN High
11	CAN Lo	CAN Low
12	CAN GND	CAN Ground

X4	I/O's	
1	Ain1	Analog input 1
2	Din4	Digital input 4
3	Din5	Digital input 5
4	Din6	Digital input 6
5	Dout1	Digital output 1
6	res.	Reserved