Servo amplifier

mcDSA-E55-Lp

Article number: 1514030

Certification: *1

Picture similar

Technical data

Absolute maximum rating (destruction limits)	
Power supply voltage Up no polarity reversal protection	80 V
Continuous Electronic supply voltage Ue no polarity reversal protection	33 V
Short term peak voltage < 1s Ue no polarity reversal protection	37 V
Power	
Electronic supply voltage Ue	9..30 V
Electronic current consumption@ Ue=24V*2	typ. 40 mA
Power supply voltage Up	9..60 V
Max. output current	50 A
Continuous output current (certified UL)*3 @Up=24V @Up=60V	 9.5 A 9 A
PWM	
PWM frequency	25, 32*4, 50 kHz
Mechanical	
Size LxWxH	70 x 50 x 18 mm
Weight	50 g
Environment	
Protection class	IP00
Operating temperature *5	-40..70 °C
Rel. humidity (non-condensing)	5..90 %
CAN bus	
Protocol	DS301
Device profile	DS402
Max. baudrate	1 Mbit/s
CAN specification	2.0B
Galvanically isolated	no

Sensor supply (Encoder/Hall)	
Output voltage	5 V
Max. output current	0.2 A
Incremental encoder	
Type	incremental
Signals	A,/A,B,/B,Inx
Max. freqency (per channel)	500 kHz
Input voltage	0..5 V
Signal type	differential, open collector, single ended
Hall sensors	
Signals	H1,H2,H3
Max. freqency (per channel)	10 kHz
Input voltage	0..5 V
Signal type	open collector, single ended
Digital inputs	
Number - digital inputs	8 (Din0..7)
Low voltage	0..5 V
High voltage	8..30 V
Digital outputs	
Number	4 (Dout0..3)
Continuous output current	0.3 A
Load	resistive, inductive
Output voltage	Electronic supply voltage Ue
Signal type	positive switching
Analog inputs	
Number	3 (Ain0..2)
Signal type - Ain0..1	+/- 10 V, 12 Bit, differential
Signal type - Ain2	0..5 V, 12 Bit, single ended

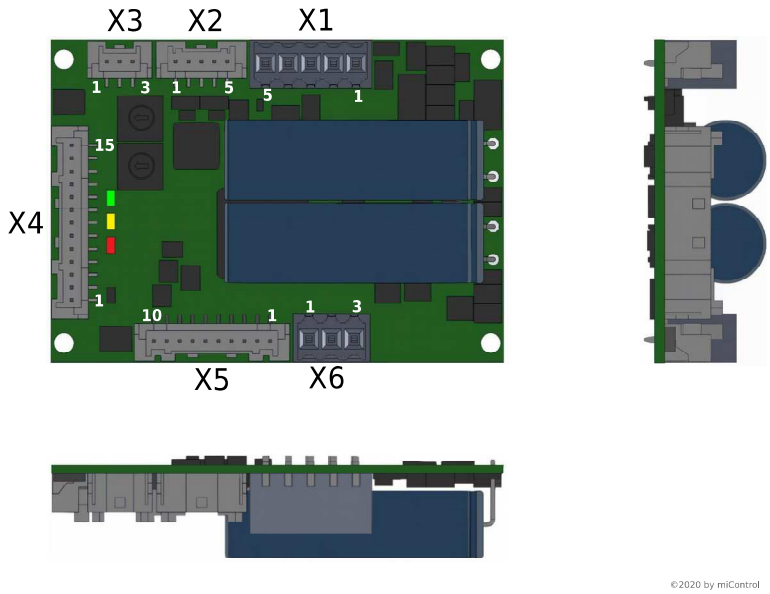
*1 take into consideration the performance data
*2 power amplifier switched off, 5V output (sensor supply) is free
*3 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C, I/O's and 5V output active
*4 default value
*5 Hex-Switches should be not used at T < -25°C(setting of node ID only possible by firmware parameters)

Additional technical data are available in mcManual.

miControl® GmbH
Chausseestraße 34
14979 Großbeeren (bei Berlin)

Web: www.miControl.de e-mail: info@miControl.de Tel.:+49 (3379) 312 59-0 Fax:+49 (3379) 312 59-19

Scheme



Terminal assignment

X1	Supply	
1	FE	Functional earth
2	+Up	Power supply voltage
3	GND	Ground for power supply voltage
4	+Ue24V	Electronic supply voltage
5	GND	Ground for electronic supply voltage
X2	**Analog inputs**	
1	+Ain0	Analog input 0, plus
2	-Ain0	Analog input 0, minus
3	+Ain1	Analog input 1, plus
4	-Ain1	Analog input 1, minus
5	Ain2	Analog Input 2 (5V)
X3	**CAN bus**	
1	CAN Hi	CAN High
2	CAN Lo	CAN Low
3	res.	Reserved
X4	**Digital inputs/outputs**	
1	res.	Reserved
2	Din0	Digital input 0
3	Din1	Digital input 1
4	Din2	Digital input 2
5	Din3	Digital input 3
6	Din4	Digital input 4
7	Din5	Digital input 5
8	Din6	Digital input 6
9	Din7	Digital input 7
10	Dout0	Digital output 0
11	Dout1	Digital output 1
12	Dout2	Digital output 2
13	Dout3	Digital output 3

X5	Hall and inc. encoder	
1	H1	Hall sensor 1
2	H2	Hall sensor 2
3	H3	Hall sensor 3
4	A	Inc. encoder, A channel
5	/A	Inc. encoder, A channel inverted
6	B	Inc. encoder, B channel
7	/B	Inc. encoder, B channel inverted
8	Inx	Inc. encoder, index channel
9	+U5V	5V output voltage for sensor supply Sensors: encoder, hall
10	GND	Ground for sensor supply Notice: don't connect with system GND
X6	**Motor**	
1	Ma	Motor phase A
2	Mb	Motor phase B
3	Mc	Motor phase C

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