

Servo amplifier

mcDSA-E55

Article number: 1513861

Certification:  *1
E475093



Picture similar

Technical data

Absolute maximum rating (destruction limits)		Sensor supply (Encoder/Hall)
Power supply voltage Up no polarity reversal protection	80 V	Output voltage 5 V
Continuous Electronic supply voltage Ue no polarity reversal protection	33 V	Max. output current 0.2 A
Short term peak voltage < 1s Ue no polarity reversal protection	37 V	Incremental encoder
Power		Type incremental
Electronic supply voltage Ue	9..30 V	Signals A./A,B./B,Inx
Electronic current consumption@ Ue=24V*2	typ. 40 mA	Max. frequency (per channel) 500 kHz
Power supply voltage Up	9..60 V	Input voltage 0..5 V
Max. output current	50 A	Signal type differential, open collector, single ended
Continuous output current @ Up=24V*3	10 A	Hall sensors
Continuous output current @ Up=48V*3	10 A	Signals H1,H2,H3
Continuous output current (certified UL)*4 @Up=24V	9.5 A	Max. frequency (per channel) 10 kHz
@Up=60V	9 A	Input voltage 0..5 V
PWM		Signal type open collector, single ended
Output voltage	100% Up	Digital inputs
PWM frequency	25, 32*5, 50 kHz	Number - digital inputs 8 (Din0..7)
Mechanical		Low voltage 0..5 V
Size LxWxH	78 x 74 x 29 mm	High voltage 8..30 V
Weight	95 g	Digital outputs
Environment		Number 4 (Dout0..3)
Protection class	IP20	Continuous output current (certified UL) 0.3 A
Ambient temperature (operation) (certified UL)	-40..40 °C	Continuous output current (not certified) 0.3 A
Ambient temperature (operation) (not certified)	-40..70 °C	Load Dout0..2 resistive, low inductive
Ambient temperature (storage)	-40..85 °C	Load Dout3 resistive, inductive
Rel. humidity (non-condensing)	5..90 %	Output voltage Electronic supply voltage Ue
CAN bus		Signal type positive switching
Protocol	DS301	Analog inputs
Device profile	DS402	Number 3 (Ain0..2)
Max. baudrate	1 Mbit/s	Signal type - Ain0..1 +/- 10 V, 12 Bit, differential
CAN specification	2.0B	Signal type - Ain2 / PT1000 0..5 V, 12 Bit, single ended / PT1000
Galvanically isolated	no	

*1 The certified performance data must be observed (see UL Instruction Note)

*2 power amplifier switched off, 5V output (sensor supply) is free

*3 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C (t > 40 °C derating), RMS current: 10 A → 8.2 Aeff no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

*4 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C, I/O's and 5V output active, RMS current: 9.5 A → 7.8 Aeff, 9 A → 7.3 Aeff

*5 default value

Additional technical data are available in mcManual.



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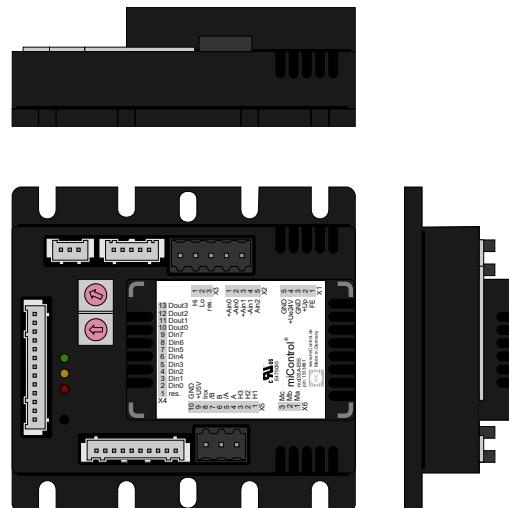
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Scheme



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Terminal assignment

X1 Supply		
1	FE	Functional earth
2	+Up	Power supply voltage
3	GND	Ground for power supply voltage
4	+Ue24V	Electronic supply voltage
5	GND	Ground for electronic supply voltage
X2 Analog inputs		
1	+Ain0	Analog input 0, plus
2	-Ain0	Analog input 0, minus
3	+Ain1	Analog input 1, plus
4	-Ain1	Analog input 1, minus
5	Ain2	Analog Input 2 (5V) / PT1000
X3 CAN bus		
1	CAN Hi	CAN High
2	CAN Lo	CAN Low
3	res.	Reserved
X4 Digital inputs/outputs		
1	res.	Reserved
2	Din0	Digital input 0
3	Din1	Digital input 1
4	Din2	Digital input 2
5	Din3	Digital input 3
6	Din4	Digital input 4
7	Din5	Digital input 5
8	Din6	Digital input 6
9	Din7	Digital input 7
10	Dout0	Digital output 0
11	Dout1	Digital output 1
12	Dout2	Digital output 2
13	Dout3	Digital output 3

X5 Hall and inc. encoder		
1	H1	Hall sensor 1
2	H2	Hall sensor 2
3	H3	Hall sensor 3
4	A	Inc. encoder, A channel
5	/A	Inc. encoder, A channel inverted
6	B	Inc. encoder, B channel
7	/B	Inc. encoder, B channel inverted
8	Inx	Inc. encoder, index channel
9	+U5V	5V output voltage for sensor supply Sensors: encoder, hall
10	GND	Ground for sensor supply Notice: don't connect with system GND
X6 Motor		
1	Ma	Motor phase A
2	Mb	Motor phase B
3	Mc	Motor phase C