miControl®

Servo amplifier

mcDSA-F17-PN

Article number: 1513807

Picture similar

Technical data

Absolute maximum rating	
Voltage (destruction limit) Up no polarity reversal protection	70 V
Continuous voltage (destruction limit) Ue no polarity reversal protection	33 V
Short term peak voltage < 1s Ue (destruction limit) no polarity reversal protection	37 V
Power	
Electronic supply voltage Ue	9..30 V
Electronic current consumption@ Ue=24V*1	typ. 60 mA
Power supply voltage Up	9..60 V
Max. output current	225 A
Continuous output current*2	70 A
PWM	
PWM frequency	32 kHz
Mechanical	
Size LxWxH	111 x 100 x 54.4 mm
Weight	584 g
Environment	
Protection class	IP20
Ambient temperature (operation)	-25..70 °C
Ambient temperature (storage)	-25..85 °C
Rel. humidity (non-condensing)	5..90 %
CAN bus	
Protocol	DS301
Device profile	DS402
Max. baudrate	1 Mbit/s
CAN specification	2.0B
Galvanically isolated	yes
PROFINET	
Type	Slave
Physical layer	100 Base-Tx
Max. baudrate	100 Mbit/s
Number of ports	2xRJ45 (PORT1, PORT2)

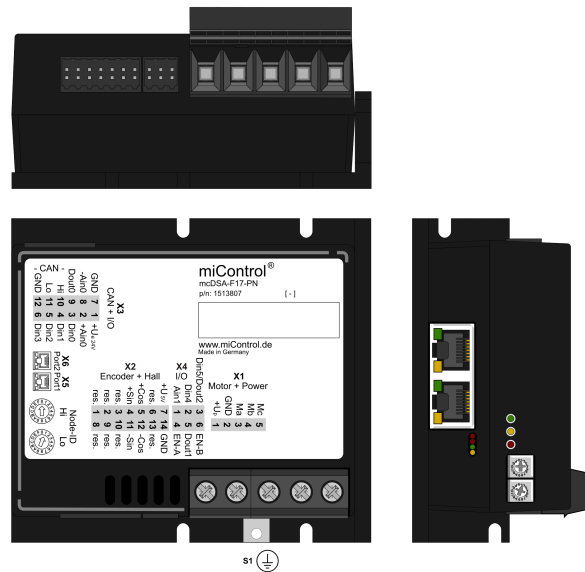| Sensor supply (Encoder)	
Output voltage	5 V
Max. output current	0.2 A
Encoder	
Type	sin / cos
Signals	+Sin,-Sin,+Cos,-Cos
Resolution	13 bit per sine period
Input voltage	1 V peak-peak, differential
Signal type	sine/cosine, analog, differential
Digital inputs	
Number - digital inputs	6 (Din0..5)
Number hardware enbable inputs	2 (EN-A..B)
Low voltage	0..5 V
High voltage	8..30 V
Notice	Din5 parallel with Dout2*3
Digital outputs	
Number	3 (Dout0..2)
Continuous output current	1.5 A
Load	resistive, inductive
Output voltage	Electronic supply voltage Ue
Signal type	positive switching
Notice	Dout2 parallel with Din5
Analog inputs	
Number	2 (Ain0..1)
Signal type - Ain0	+/- 10 V, 12 Bit, differential
Signal type - Ain1	+/- 10 V, 12 Bit, single ended

*1 power amplifier switched off, 5V output (sensor supply) is free
*2 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C (t >40 °C derating), RMS current: 70 A → 50 Aeff
no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current
*3 Input voltage must not exceed Electronic supply voltage Ue

Additional technical data are available in mcManual.

Scheme

Terminal assignment

X1	Motor	
1	+Up	Power supply voltage
2	GND	Ground for power supply voltage
3	Ma	Motor phase A
4	Mb	Motor phase B
5	Mc	Motor phase C
X2	Encoder	
1	res.	Reserved
2	res.	Reserved
3	res.	Reserved
4	+Sin	Encoder, plus sine signal
5	+Cos	Encoder, plus cosine signal
6	res.	Reserved
7	+U5V	5V output voltage for sensor supply Sensors: encoder
8	res.	Reserved
9	res.	Reserved
10	res.	Reserved
11	-Sin	Encoder, minus sine signal
12	-Cos	Encoder, minus cosine signal
13	res.	Reserved
14	GND	Ground for sensor supply Notice: don't connect with system GND
X3	I/O's and CAN	
1	+Ue24V	Electronic supply voltage
2	+Ain0	Analog input 0, plus
3	Din0	Digital input 0
4	Din1	Digital input 1
5	Din2	Digital input 2
6	Din3	Digital input 3
7	GND	Ground for electronic supply voltage
8	-Ain0	Analog input 0, minus
9	Dout0	Digital output 0
10	CAN Hi	CAN High
11	CAN Lo	CAN Low
12	CAN GND	CAN Ground

X4	I/O's	
1	Ain1	Analog input 1
2	Din4	Digital input 4
3	Din5/Dout2	Digital input 5 / Digital output 2
4	EN-A	Hardware enable channel A
5	Dout1	Digital output 1
6	EN-B	Hardware enable channel B
S1	Screw (M4)	
-	FE	Functional earth
X5	PROFINET - PORT1	
-	PORT1	PORT1
X6	PROFINET - PORT2	
-	PORT2	PORT2