

Servo amplifier

mcDSA-F55-SSI

Article number: 1515992



Picture similar

Technical data

| Supply voltages | |
|---|---------------------|
| Electronic supply voltage U_e^{*1} | 9..30 V |
| Electronic current consumption @ $U_e=24V^{*2}$ | typ. 60 mA |
| Power supply voltage U_p^{*3} | 9..60 V |
| Output current | |
| Max. output current | 50 A |
| Continuous output current @ $U_p=24V^{*4}$ | 14.5 A |
| Continuous output current @ $U_p=48V^{*5}$ | 13 A |
| PWM | |
| PWM frequency | 32 kHz |
| Mechanical | |
| Size LxWxH | 78 x 74 x 49 mm |
| Weight | 145 g |
| Environment | |
| Protection class | IP20 |
| Ambient temperature (operation) ^{*6} | -40..70 °C |
| Ambient temperature (storage) | -40..85 °C |
| Rel. humidity (non-condensing) | 5..90 % |
| CAN bus | |
| Protocol | DS301 |
| Device profile | DS402 |
| Max. baudrate | 1 Mbit/s |
| CAN specification | 2.0B |
| Galvanically isolated | yes |
| RS485 | |
| Type | 2-Wire EIA-485 |
| Signals | DATA,/DATA,CLK,/CLK |
| Sensor supply (Encoder/Hall/SSI) | |
| Output voltage | 5 V |
| Max. output current | 0.2 A |

| Incremental encoder | |
|---------------------------------|--|
| Type | incremental |
| Signals | A,/A,B,/B,Inx |
| Max. frequency (per channel) | 500 kHz |
| Input voltage (24V tolerant) | 0..5 V |
| Signal type | differential, open collector, single ended |
| Hall sensors | |
| Signals | H1,H2,H3 |
| Max. frequency (per channel) | 10 kHz |
| Input voltage | 0..5 V |
| Signal type | open collector, single ended |
| Digital inputs | |
| Number - digital inputs | 7 (Din0..6) |
| Number - hardware enable inputs | 2 (EN-A..B) |
| Low voltage | 0..5 V |
| High voltage | 8..30 V |
| Digital outputs | |
| Number | 4 (Dout0..3) |
| Continuous output current | 0.3 A |
| Load | resistive, inductive |
| Output voltage | Electronic supply voltage U_e |
| Signal type | positive switching |
| Analog inputs | |
| Number | 3 (Ain0..2) |
| Signal type - Ain0..1 | +/- 10 V, 12 Bit, differential |
| Signal type - Ain2 / PT1000 | 0..5 V, 12 Bit, single ended / PT1000 |

*1 No reverse polarity protection, the destruction limit is at overvoltage of $\geq 33V$ or short-term peak voltage of $37V < 1s$

*2 power amplifier switched off, 5V output (sensor supply) is free

*3 No reverse polarity protection, the destruction limit is at overvoltage of $\geq 70V$

*4 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C ($t > 40$ °C derating), RMS current: 14.5 A \rightarrow 10.3 Aeff

no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

*5 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C ($t > 40$ °C derating), RMS current: 13 A \rightarrow 9.2 Aeff

no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

*6 Hex-Switches should be not used at $T < -25^\circ C$ (setting of node ID only possible by firmware parameters)

Additional technical data are available in mcManual.



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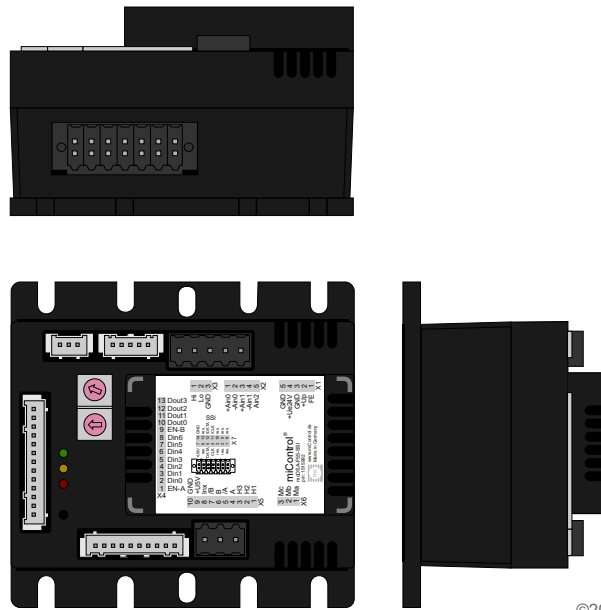
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Scheme



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Terminal assignment

| X1 Supply | | |
|---------------------------|---------|--------------------------------------|
| 1 | FE | Functional earth |
| 2 | +Up | Power supply voltage |
| 3 | GND | Ground for power supply voltage |
| 4 | +Ue24V | Electronic supply voltage |
| 5 | GND | Ground for electronic supply voltage |
| X2 Analog inputs | | |
| 1 | +Ain0 | Analog input 0, plus |
| 2 | -Ain0 | Analog input 0, minus |
| 3 | +Ain1 | Analog input 1, plus |
| 4 | -Ain1 | Analog input 1, minus |
| 5 | Ain2 | Analog Input 2 (5V) / PT1000 |
| X3 CAN bus | | |
| 1 | CAN Hi | CAN High |
| 2 | CAN Lo | CAN Low |
| 3 | CAN GND | CAN Ground |
| X4 Digital inputs/outputs | | |
| 1 | EN-A | Hardware enable channel A |
| 2 | Din0 | Digital input 0 |
| 3 | Din1 | Digital input 1 |
| 4 | Din2 | Digital input 2 |
| 5 | Din3 | Digital input 3 |
| 6 | Din4 | Digital input 4 |
| 7 | Din5 | Digital input 5 |
| 8 | Din6 | Digital input 6 |
| 9 | EN-B | Hardware enable channel B |
| 10 | Dout0 | Digital output 0 |
| 11 | Dout1 | Digital output 1 |
| 12 | Dout2 | Digital output 2 |
| 13 | Dout3 | Digital output 3 |

| X5 Hall and inc. encoder | | | |
|--------------------------|-------|---|--|
| 1 | H1 | Hall sensor 1 | |
| 2 | H2 | Hall sensor 2 | |
| 3 | H3 | Hall sensor 3 | |
| 4 | A | Inc. encoder, A channel | |
| 5 | /A | Inc. encoder, A channel inverted | |
| 6 | B | Inc. encoder, B channel | |
| 7 | /B | Inc. encoder, B channel inverted | |
| 8 | Inx | Inc. encoder, index channel | |
| 9 | +U5V | 5V output voltage for sensor supply Sensors: encoder, hall | |
| 10 | GND | Ground for sensor supply Notice: don't connect with system GND | |
| X6 Motor | | | |
| 1 | Ma | Motor phase A | |
| 2 | Mb | Motor phase B | |
| 3 | Mc | Motor phase C | |
| X7 Encoder | | | |
| 1 | res. | Reserved | |
| 2 | res. | Reserved | |
| 3 | res. | Reserved | |
| 4 | CLK | SSI clk | |
| 5 | DATA | SSI data | |
| 6 | res. | Reserved | |
| 7 | +U5V | 5V output voltage for sensor supply Sensors: encoder, SSI | |
| 8 | res. | Reserved | |
| 9 | res. | Reserved | |
| 10 | res. | Reserved | |
| 11 | /CLK | /SSI clk | |
| 12 | /DATA | /SSI data | |
| 13 | res. | Reserved | |
| 14 | GND | Ground for sensor supply Notice: don't connect with system GND | |